

TIKHONOV REGULARIZATION FOR A CLASS OF ILL-POSED VARIATIONAL INEQUALITIES¹

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Abstract. *The aim of this paper is to investigate a problem of variational inequalities with a constraint in the form of ill-posed nonlinear operator equation involving monotone operators under monotone perturbations. A result on convergence rate for the Tikhonov regularization is established. Then, this result will be considered in combination with finite-dimensional approximations of the space. For illustration, an example in the theory of linear integral equations in L_p -space is given.*

1. INTRODUCTION

Many problems arising in mathematical physics and mechanics (see e.g. [4, 5, 7, 20, 23]) have been formulated in the following abstract form: find an element $x_0 \in S_0$ such that

$$\varphi(x_0) = \min_{x \in S_0} \varphi(x), \quad (1)$$

where φ is a weakly lower semicontinuous and properly convex functional on the real reflexive Banach space X with the norm denoted by $\|\cdot\|$, and S_0 is a convex and closed subset of X . If we denote by $A(x)$ the subdifferential of the functional φ at the point x , then this problem is equivalent to the variational inequality (see [23])

$$\langle A(x_0), x - x_0 \rangle \geq 0, \quad \forall x \in S_0, \quad x_0 \in S_0, \quad (2)$$

where the symbol $\langle x^*, x \rangle$ denotes the value of the linear continuous functional $x^* \in X^*$ at the point $x \in X$ and X^* is the adjoint space of X . For the sake of simplicity, the norm of X^* will be also denoted by the symbol $\|\cdot\|$.

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Up to now, there have been a lot of works dealing not only with theoretical aspects but also numerical methods and applications of this problem (see [3, 9, 10, 11, 14, 18–20, 25, 26]). Moreover, some results have been generalized for locally Lipschitzian functional φ (see [6]) and recently for invex functional (see [13]).

In [15, 22, 23] one considered an interesting case, when φ is convex, and S_0 is the set of all solutions of the other operator equation

$$F(x) = f_0, \quad f_0 \in X^*, \quad (3)$$

where F is a monotone operator from X into X^* . It is well known (see [1]) that, without additional conditions on the structure of F such as strong or uniform monotonicity, equation (3) is, in general, an ill-posed problem (see [24]). By this we mean that solutions of (3) do not depend continuously on the data F, f_0 . Therefore, the problem (2) in this case is ill-posed, too. To solve it we have to use stable methods. A widely used method of this kind is the Tikhonov regularization in the form of operator equation

$$F_h(x) + \alpha A(x) = f_\delta, \quad (4)$$

where F_h and f_δ are respectively the approximations for F and f_0 ,

$$\|F(x) - F_h(x)\| \leq h\|x\|, \quad \forall x \in X, \quad \|f_\delta - f_0\| < \delta, \quad h, \delta \rightarrow 0,$$

and α is the parameter of regularization. If F_h are monotone and hemicontinuous, and A is uniform monotone, then the existence and uniqueness of the solution of (4) were proved in [5, 22, 23]. There one has also showed that if δ/α and $h/\alpha \rightarrow 0$ this solution converges to x_0 and it can be approximated by solutions of the sequence of finite-dimensional problems (see [21])

$$F_{hn}(x) + \alpha A_n(x) = f_{\delta n}, \quad (5)$$

where $F_{hn} = P_n^* F_h P_n$, $A_n = P_n^* A P_n$, $f_{\delta n} = P_n^* f_\delta$ and P_n denotes the linear projection from X onto its subspace X_n satisfying the condition

$$X_n \subset X_{n+1}, \quad P_n x \rightarrow x, \quad n \rightarrow +\infty, \quad \forall x \in X,$$

and P_n^* is the adjoint of P_n , $\|P_n\| \leq c$, where c is a positive constant.

Until now, it is still open the question whether $\lim_{\substack{\alpha, h, \delta \rightarrow 0 \\ n \rightarrow +\infty}} x_{h\alpha n}^\delta = x_0$, where $\{x_{h\alpha n}^\delta\}$, is the sequence of solutions of (5) and also the question

about its convergence rate, as well as about the convergence rate for $\{x_{h\alpha}^\delta\}$, the solution of (4).

Obviously, the answer for these questions depend on the relation between h , α and n . In this paper, applying the ideas of Engl and Groetsch in [8, 12] we shall answer these questions, under the assumption that A is an uniformly monotone operator, i. e.

$$\langle A(x) - A(y), x - y \rangle \geq m_A \|x - y\|^s, \quad 1 < s < +\infty, \quad (6)$$

where m_A is a positive constant. Without loss of generality, we shall assume $m_A = 1$.

Below the symbols \rightarrow and \rightharpoonup denote the strong and weak convergence for any sequence, respectively.

2. MAIN RESULTS

First we prove a result about convergence rate for the sequence $\{x_{h\alpha}^\delta\}$

Theorem 1. *Suppose that the following conditions hold:*

- (i) F_h is Fréchet differentiable in some neighbourhood of S_0 $s - 1$ -times if $s = [s]$; the integer part of s , and $[s]$ -times if $s \neq [s]$;
- (ii) The derivative $F_h^{(k)}$ satisfies the condition

$$\|F_h^{(k)}(x) - F_h^{(k)}(y)\| \leq L \|x - y\|, \quad \forall x \in S_0, y \in U_0, L > 0,$$

where U_0 is a neighbourhood of S_0 and $k = s - 1$ if $s = [s]$, and $k = [s]$ if $s \neq [s]$. Moreover, if $[s] \geq 3$, $F_h^{(2)}(x_0) = \dots = F_h^{(k)}(x_0) = 0$;

- (iii) There exist elements z_h of X such that

$$F_h'^*(x_0)z_h = A(x_0)$$

and $L \|z_h\| \leq s!$ if $s = [s]$.

Then, if α is chosen such that $\alpha \sim (h + \delta)^\theta$, $0 < \theta < 1$, we have

$$\|x_{h\alpha}^\delta - x_0\| = O((h + \delta)^\rho), \quad \rho = \min \{(1 - \theta)/(s - 1), \theta/s\}.$$

Proof. From (3) and (4) it follows

$$\alpha \langle A(x_{h\alpha}^\delta) - A(x_0), x_{h\alpha}^\delta - x_0 \rangle \leq \langle f_\delta - f_0, x_{h\alpha}^\delta - x_0 \rangle + \langle F(x_0) - F_h(x_0), x_{h\alpha}^\delta - x_0 \rangle + \alpha \langle A(x_0), x_0 - x_{h\alpha}^\delta \rangle.$$

Combining this inequality, (6) and condition (iii) gives

$$\alpha \|x_{h\alpha}^\delta - x_0\|^s \leq (\delta + h\|x_0\|) \|x_{h\alpha}^\delta - x_0\| + \alpha \langle z_h, F_h'(x_0)(x_0 - x_{h\alpha}^\delta) \rangle. \quad (7)$$

In the case $s = [s]$, since

$$F_h'(x_0)(x_0 - x_{h\alpha}^\delta) = F_h(x_0) - F_h(x_{h\alpha}^\delta) + r_{h\alpha}^\delta$$

with

$$\|r_{h\alpha}^\delta\| \leq \frac{L}{s!} \|x_{h\alpha}^\delta - x_0\|^s$$

(see [26]) from (7) it follows that

$$\alpha \|x_{h\alpha}^\delta - x_0\|^s \leq (\delta + h\|x_0\|) \|x_{h\alpha}^\delta - x_0\| + \alpha \frac{L}{s!} \|z_h\| \|x_{h\alpha}^\delta - x_0\|^s + \alpha \langle z_h, F_h(x_0) - F_h(x_{h\alpha}^\delta) \rangle.$$

We can estimate the last term in the following way

$$\begin{aligned} \langle z_h, F_h(x_0) - F_h(x_{h\alpha}^\delta) \rangle &= \langle z_h, F_h(x_0) - F(x_0) + f_0 - f_\delta + \alpha A(x_{h\alpha}^\delta) \rangle \\ &\leq \|z_h\| (\delta + h\|x_0\| + \alpha \|A(x_{h\alpha}^\delta)\|), \end{aligned}$$

that is equivalent to $\sim \delta + h + \alpha$ because $x_{h\alpha}^\delta \rightarrow x_0$ and the hemicontinuous monotone operator A is locally bounded (see [25]). Thus, the inequality (7) can be written in the form

$$\left(1 - \frac{L}{s!} \|z_h\|\right) \|x_{h\alpha}^\delta - x_0\|^s \leq \frac{h\|x_0\| + \delta}{\alpha} \|x_{h\alpha}^\delta - x_0\| + O(h + \delta + \alpha). \quad (8)$$

Using the implication in [17]:

$$a, b > 0, p > q > 0 \text{ and } t^p \leq at^q + b \Rightarrow t^p = O(a^{p/(p-q)} + b)$$

we get

$$\|x_{h\alpha}^\delta - x_0\| = O((h + \delta)^\rho).$$

If $s \neq [s]$, the left-hand side of the inequality (8) will be replaced by

$$\left(1 - \frac{L}{([s] + 1)!} \|z\| \|x_{h\alpha}^\delta - x_0\|^{[s]+1-s}\right) \|x_{h\alpha}^\delta - x_0\|^s.$$

As $[s] + 1 - s > 0$ and $\|x_{h\alpha}^\delta - x_0\| \rightarrow 0$, the requirement $L\|z_h\| \leq s!$ is not necessary. Q.E.D.

The following theorem is the answer for the question about the convergence of $\{x_{h\alpha n}^\delta\}$.

Theorem 2. *If the conditions (i) and (ii) of Theorem 1 hold. Moreover, suppose additionally that*

(iv) *There exists $\alpha = \alpha(n) \rightarrow 0$ such that*

$$(\tilde{\gamma}_{hn}(x) + \|(I - P_n)x\|^{[s]})\alpha^{-1} \rightarrow 0, \forall x \in S_0,$$

as $h, \delta \rightarrow 0$ and $n \rightarrow +\infty$, where $\tilde{\gamma}_{hn}(x)$ is defined by

$$\tilde{\gamma}_{hn}(x) = \|F'_h(x)(I - P_n)x\|.$$

Then the sequence $\{x_{h\alpha n}^\delta\}$ converges to x_0 .

Proof. From (5) it follows

$$\begin{aligned} F_{hn}(x_{h\alpha n}^\delta) - F_{hn}(x_n) + \alpha(A_n(x_{h\alpha n}^\delta) - A_n(x_n)) \\ = f_{\delta n} - F_{hn}(x_n) - \alpha A_n(x_n), \quad x_n = P_n x, \quad \forall x \in S_0. \end{aligned}$$

Multiplying the two parts of this equality by $x_{h\alpha n}^\delta - x_n$, and using the projective property of P_n : $P_n^* = P_n^* P_n^*$ and the monotone property of F_{hn} and A , we obtain

$$\begin{aligned} \alpha \langle A(x_{h\alpha n}^\delta) - A(x_n), x_{h\alpha n}^\delta - x_n \rangle &\leq (\delta + h\|x\|) \|x_{h\alpha n}^\delta - x_n\| \\ &+ \langle F_h(x) - F_h(x_n), x_{h\alpha n}^\delta - x_n \rangle + \alpha \langle A(x_n), x_n - x_{h\alpha n}^\delta \rangle. \end{aligned} \quad (9)$$

In the case $s = [s]$ we can write

$$F_h(x_n) = F_h(x) + F'_h(x)(x_n - x) + r_{hn}$$

with

$$\|r_{hn}\| \leq \frac{L}{s!} \|(I - P_n)x\|^s.$$

Therefore, from (6) and (9) we get

$$\begin{aligned} \alpha \|x_{h\alpha n}^\delta - x_n\|^s &\leq \\ &\leq (\delta + h\|x\| + \frac{L}{s!} \|(I - P_n)x\|^s + \|F'_h(x)(I - P_n)x\|) \|x_{h\alpha n}^\delta - x_n\| \\ &\quad + \alpha \langle A(x_n), x_n - x_{h\alpha n}^\delta \rangle. \end{aligned} \quad (10)$$

Because of $s > 1$, this inequality gives us the boundedness of the sequence $\{x_{h\alpha n}^\delta\}$. Without loss of generality, suppose that $x_{h\alpha n}^\delta \rightarrow x_1 \in X$, as $n \rightarrow +\infty$ and $h, \alpha, \delta \rightarrow 0$. We shall prove that $x_1 \in S_0$.

First, since $F_n := P_n^* F P_n$ is monotone, we have

$$\langle F_n(x_n) - F_n(x_{h\alpha n}^\delta), x_n - x_{h\alpha n}^\delta \rangle \geq 0, \quad x_n = P_n x, \quad \forall x \in X.$$

Since $P_n^* P_n^* = P_n^*$, this inequality can be written in the form

$$\langle F(x_n) - F_n(x_{h\alpha n}^\delta), x_n - x_{h\alpha n}^\delta \rangle \geq 0.$$

Together with (5), it gives

$$\begin{aligned} &\langle F(x_n) - f_{\delta n} + \alpha A_n(x_{h\alpha n}^\delta), x_n - x_{h\alpha n}^\delta \rangle \\ &\quad + \langle F_{hn}(x_{h\alpha n}^\delta) - F_n(x_{h\alpha n}^\delta), x_n - x_{h\alpha n}^\delta \rangle \geq 0, \end{aligned}$$

that is equivalent to

$$\begin{aligned} &\langle F(x_n) - f_\delta, x_n - x_{h\alpha n}^\delta \rangle + \alpha \langle A(x_n), x_n - x_{h\alpha n}^\delta \rangle \\ &\quad + \langle F_h(x_{h\alpha n}^\delta) - F(x_{h\alpha n}^\delta), x_n - x_{h\alpha n}^\delta \rangle \geq 0. \end{aligned}$$

Thus we have

$$\begin{aligned} &h \|x_{h\alpha n}^\delta\| \|x_n - x_{h\alpha n}^\delta\| + \langle F(x_n) - f_\delta, x_n - x_{h\alpha n}^\delta \rangle \\ &\quad + \alpha \langle A(x_n), x_n - x_{h\alpha n}^\delta \rangle \geq 0. \end{aligned}$$

Letting $n \rightarrow +\infty$ and $h, \delta, \alpha \rightarrow 0$ we obtain

$$\langle F(x) - f_0, x - x_1 \rangle \geq 0, \quad \forall x \in X.$$

By virtue of Minty's lemma, $x_1 \in S_0$. Replacing x_n in (10) by $x_{1n} = P_n x_1$ and letting $n \rightarrow +\infty$ and $h, \delta, \alpha \rightarrow 0$, we can see that $x_{h\alpha n}^\delta \rightarrow x_1$ and

$$\langle A(x), x - x_1 \rangle \geq 0, \forall x \in S_0.$$

On the other hand, this variational inequality is equivalent to

$$\langle A(x_1), x - x_1 \rangle \geq 0, \forall x \in S_0.$$

Therefore, x_1 is a solution of the problem (1) (see [23]). Since A is uniformly monotone, the last variational inequality has a unique solution x_0 . Thus, $x_1 = x_0$ and the entire sequence $\{x_{h\alpha n}^\delta\}$ converges to x_0 .

For the case $s \neq [s]$, the term $\frac{L}{s!} \|(I - P_n)x\|^s$ in (10) will be replaced by $\frac{L}{([s]+1)!} \|(I - P_n)x\|^{[s]+1}$ and the process of proof of the theorem will be entirely repeated. Q.E.D.

It is not difficult to verify that all results in Theorems 1 and 2 are still true, if all conditions on F_h are stated in the similar way only for F , i.e. the index h in Theorems 1 and 2 for F_h , its derivatives, z_h and $\tilde{\gamma}_{hn}$ can be omitted. Indeed, for instance, in the proof of Theorem 2 the inequalities (9) and (10) will be replaced by

$$\begin{aligned} \alpha \langle A(x_{h\alpha n}^\delta) - A(x_n), x_{h\alpha n}^\delta - x_n \rangle &\leq (\delta + h\|x\|) \|x_{h\alpha n}^\delta - x_n\| \\ &+ \langle F(x) - F(x_n), x_{h\alpha n}^\delta - x_n \rangle + \alpha \langle A(x_n), x_n - x_{h\alpha n}^\delta \rangle. \end{aligned} \quad (9')$$

$$\begin{aligned} \alpha \|x_{h\alpha n}^\delta - x_n\|^s &\leq \\ &\leq (\delta + h\|x\| + \frac{L}{s!} \|(I - P_n)x\|^s + \|F'(x)(I - P_n)x\|) \|x_{h\alpha n}^\delta - x_n\| \\ &+ \alpha \langle A(x_n), x_n - x_{h\alpha n}^\delta \rangle. \end{aligned} \quad (10')$$

respectively, and the process of proof of the theorem is completely repeated. We will do this in detail in answering the question about convergence rate for the sequence $\{x_{h\alpha n}^\delta\}$.

Theorem 3. *Let the conditions (i)–(iii) of Theorem 1 hold for F . Moreover, let*

- (v) *There exists a positive constant d and a neighbourhood O_0 of x_0 such that*

$$\|A(x) - A(x_0)\| \leq d\|x - x_0\|^{\tilde{s}}, \quad \tilde{s} > 0, \quad \forall x \in O_0;$$

- (vi) *α is chosen such that $\alpha \sim (h + \delta + \gamma_n)^{1/2}$, where*

$$\gamma_n = \max \{ \|(I - P_n)x_0\|, \|(I^* - P_n^*)f_0\|, \|(I - P_n)z\| \}.$$

Then

$$\|x_{h\alpha n}^\delta - x_0\| = O((h + \delta)^{1/2s} + \gamma_n^{\bar{s}}), \quad \bar{s} = \min \{1/2s, \tilde{s}\}.$$

Proof. From the condition (v) of this theorem, for sufficiently large n , we have

$$\begin{aligned} \langle A(x_{0n}), x_n - x_{h\alpha n}^\delta \rangle &\leq d\gamma_n^{\tilde{s}} \|x_{h\alpha n}^\delta - x_n\| \\ &+ \langle A(x_0), x_n - x_{h\alpha n}^\delta \rangle, \quad x_n \in X_n. \end{aligned}$$

Thus, in the case $s = [s]$, the inequality (10') with $x_n = x_{0n}$ has the form

$$\begin{aligned} \alpha \|x_{h\alpha n}^\delta - x_{0n}\|^s &\leq O(\delta + h\|x_0\| + \gamma_n + \gamma_n^s + \alpha d\gamma_n^{\tilde{s}}) \|x_{h\alpha n}^\delta - x_{0n}\| \\ &+ \alpha \langle A(x_0), x_{0n} - x_{h\alpha n}^\delta \rangle. \end{aligned} \quad (11)$$

It is easy to see that in this case of s

$$\begin{aligned} \langle A(x_0), x_{0n} - x_{h\alpha n}^\delta \rangle &= \langle A(x_0), (P_n - I)x_0 \rangle + \langle z, F'(x_0)(x_0 - x_{h\alpha n}^\delta) \rangle \\ &\leq O(h + \gamma_n) + \langle z, F(x_0) - F_h(x_{h\alpha n}^\delta) \rangle + L\|z\| \|x_{h\alpha n}^\delta - x_0\|^s/s!, \\ \|x_{h\alpha n}^\delta - x_0\|^s &\leq \|x_{h\alpha n}^\delta - x_{0n}\|^s + O(\gamma_n), \end{aligned}$$

and

$$\begin{aligned} \langle z, F(x_0) - F_h(x_{h\alpha n}^\delta) \rangle &= \langle z, f_0 - f_\delta \rangle + \alpha \langle z, A(x_{h\alpha}^\delta) \rangle \\ &+ \langle z, F_h(x_{h\alpha}^\delta) - F_h(x_{h\alpha n}^\delta) \rangle \\ &\leq O(\delta + \alpha) + \langle z, F_h(x_{h\alpha}^\delta) - F_h(x_{h\alpha n}^\delta) \rangle. \end{aligned}$$

Since

$$\begin{aligned} \langle z, F_h(x_{h\alpha}^\delta) - F_h(x_{h\alpha n}^\delta) \rangle &= \langle z, F_h(x_{h\alpha}^\delta) - F_{hn}(x_{h\alpha n}^\delta) \rangle \\ &+ \langle z, F_{hn}(x_{h\alpha n}^\delta) - F_h(x_{h\alpha n}^\delta) \rangle, \end{aligned}$$

where

$$\begin{aligned} \langle z, F_{hn}(x_{h\alpha n}^\delta) - F_h(x_{h\alpha n}^\delta) \rangle &= \langle (P_n - I)z, F_h(x_{h\alpha n}^\delta) \rangle \\ &\leq \gamma_n \|F_h(x_{h\alpha n}^\delta) - F(x_{h\alpha n}^\delta) + F(x_{h\alpha n}^\delta)\| \leq O(\gamma_n) \end{aligned}$$

and

$$\begin{aligned} \langle z, F_h(x_{h\alpha}^\delta) - F_{hn}(x_{h\alpha n}^\delta) \rangle &= \langle z, f_\delta - \alpha A(x_{h\alpha}^\delta) - f_{\delta n} + \alpha A_n(x_{h\alpha n}^\delta) \rangle \\ &\leq O(\delta + \alpha) + \langle z, (I^* - P_n^*)f_0 \rangle \leq O(\gamma_n + \delta + \alpha). \end{aligned}$$

The inequality (11) can be written in the form

$$\begin{aligned} \alpha(1 - L\|z\|/s!) \|x_{h\alpha n}^\delta - x_{0n}\|^s &\leq O(h + \delta + \gamma_n + \gamma_n^s + \alpha d \tilde{\gamma}_n^s) \|x_{h\alpha n}^\delta - x_{0n}\| \\ &\quad + \alpha O(h + \delta + \alpha + \gamma_n). \end{aligned}$$

Then

$$\begin{aligned} \|x_{\alpha n}^\delta - x_{0n}\|^s &\leq O((h + \delta + \gamma_n)^{1/2} + \gamma_n^{s/2} + \tilde{\gamma}_n^s) \|x_{\alpha n}^\delta - x_{0n}\| \\ &\quad + O((h + \delta + \alpha + \gamma_n)). \end{aligned}$$

Applying again the relation in [17] to the last inequality we obtain

$$\|x_{\alpha n}^\delta - x_{0n}\| \leq O((h + \delta)^{1/2s} + \tilde{\gamma}_n^{\bar{s}}).$$

Therefore

$$\|x_{\alpha n}^\delta - x_0\| \leq O((h + \delta)^{1/2s} + \tilde{\gamma}_n^{\bar{s}}).$$

The case $s \neq [s]$ is proved in the similar way as in the proof of Theorem 1. Q.E.D.

3. AN EXAMPLE

Consider the following problem: find a norm-minimal solution of the linear integral equation

$$(Fx)(t) \equiv KfK^*x(t) = f_0(t), \quad t \in \Omega, \quad (12)$$

for a given $f_0(x) \in L_q(\Omega)$, $1 < q < +\infty$. Here the operator K is defined by

$$(Kx)(t) = \int_{\Omega} k(t, s) x(s) ds, \quad t \in \Omega,$$

where the kernel function $k(t, s)$ is a measurable on $\Omega \times \Omega$ such that the null space $\mathcal{N}(K) \neq \{O\}$ and Ω is a closed set in \mathbf{R}^n . The function $f(t)$, $t \in \mathbf{R}^1$, is a real and non-decreasing function.

Suppose

$$\int_{\Omega \times \Omega} |k(x, y)|^q < +\infty, \quad |f(t)| \leq b_0 + b_1 |t|^{q-1}, \quad b_0, b_1 > 0, \quad p^{-1} + q^{-1} = 1.$$

Then the operator K is a linear, bounded operator from $X = L_p(\Omega)$ into $X^* = L_q(\Omega)$, and $(fx)(t) = f(x(t)) : X^* \rightarrow X$, is a monotone operator. Therefore, $F = KfK^*$ is also a monotone operator from X into X^* . If either K or f is compact, then (12) is ill-posed. We are interested in a solution $x_0(t)$ of (12) with minimal norm. In this case, the operator A is the dual mapping U^s of the spaces L_p . It satisfies all necessary conditions (see [2]): If X is a Hilbert space, then $U^s = I$, $s = 2$, $m_A = 1$, $\tilde{s} = 1$ and $d = c(R) = 1$, $R = \max\{\|x\|, \|x_0\|\}$. For the spaces of Lebesgue's type l_p , L_p , W_m^p , $p > 1$ we can construct U^s satisfying condition (6) and the condition (v) of Theorem 3 with

$$1 < p < 2 : s = 2, \quad m_A = p - 1, \quad c(\rho) = p^{2^{2p-1}} e^p L^{p-1},$$

$$e = \max\{2^p, 2\rho\}, \quad 1 < L < 3.18, \quad \tilde{s} = p - 1;$$

$$2 < p : s = p, \quad m_A = 2^{2-p}/p,$$

$$c(\rho) = 2^p \rho^{p-2} \{p[p-1 + \max\{\rho, L\}]\}^{-1}, \quad \tilde{s} = 1.$$

In particular, if $1 < p < 2$, then $s = 2$ and we only need to verify the condition (iii) of Theorem 1 and the condition (iv) of Theorem 2 for each concrete problem and concrete form of finite-dimensional approximations of $L_p(\Omega)$. We shall see this in the following case, when $\Omega = [0, 1]$, $p = 2$. Then condition (iii) of Theorem 1 is written in the form

$$x_0 = K f_h'^*(K^* x_0) K^* z_h,$$

where f_h is the approximations of f . This equation has solution if $x_0 \in R(K)$, the range of K , and there exist $u_h(t) \in R(K^*)$ such that

$$\xi_0 = f_h'^*(y_0)u_h, \quad y_0 = K^*x_0, \quad K\xi_0 = x_0, \quad (13)$$

where $f_h'^*(y_0)$ is coercive on $L_2[0, 1]$.

Indeed, let for example

$$f(t) = \begin{cases} e_1(t - t_0) + d, & \text{if } t - t_0 \leq 0, \\ e_2(t - t_0) + d, & \text{if } t - t_0 > 0, \end{cases}$$

$$e_2 > e_1 > 0, \quad d \in R.$$

Then we can approximate $f(t)$ by $f_h(t)$ in the following form

$$f_h(t) = \begin{cases} f(t), & \text{if } t \notin (t_0 - h, t_0 + h), \\ d + e_1(t - t_0) + p(t - t_0 + h)^2 \\ + q(t - t_0 + h)^3, & \text{if } t \in (t_0 - h, t_0 + h). \end{cases}$$

The coefficients p and q can be calculated by solving the system of two linear equations

$$f_h(t_0 + h) = e_2h + d, \\ f_h'(t_0 + h) = e_2.$$

It is easy to verify that for sufficiently small h the coefficients p and q are defined uniquely and the functions $f_h(t)$ are monotone and differentiable. Moreover

$$|F_{1h}(t) - f(t)| \leq |F_{1h}(t_0) - F(t_0)| \leq ch, \quad c > 0.$$

On the other hand, we have

$$f_h'(t) = \begin{cases} e_1 \text{ or } e_2, & \text{if } t \notin (t_0 - h, t_0 + h), \\ e_1 + (e_2 - e_1)(t - t_0 + h)/4h, & \text{if } t \in [t_0 - h, t_0 + h]. \end{cases}$$

Therefore, condition (13) is satisfied, because $e_1 > 0$. Now, we approximate the Hilbert space $H = L_2[0, 1]$ by the sequence of linear subspaces H_n , defined by

$$H_n = L\{\psi_1, \psi_2, \dots, \psi_n\}, \\ \psi_j = \begin{cases} 1, & t \in (t_{j-1}, t_j], \\ 0, & t \notin (t_{j-1}, t_j]. \end{cases}$$

It is well known that

$$\|(I - P_n)y\| = O(n^{-1}), \quad \forall y \in L_2[0, 1],$$

where

$$P_n y = \sum_{j=1}^n y(t_j) \psi_j(t).$$

By taking $\alpha_n = O(n^{-1/2})$ and $h = \delta = O(n^{-2})$ we can see that almost all the conditions of Theorems 1–3 are satisfied.

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