

RDS for climate

Lecture 2: NADS and their attractors

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A question from the previous lecture

Recall the problem

$$\int_X \phi(x) \mu_q(t)(dx) = \lim_{\epsilon \rightarrow 0} \frac{1}{2\delta_\epsilon} \int_{t-\delta_\epsilon}^{t+\delta_\epsilon} \left(\int_X \phi(y) \mu_{q,\omega}^\epsilon(s)(dy) \right) ds.$$

Which is the intuition behind

$$\frac{1}{2\delta_\epsilon} \int_{t-\delta_\epsilon}^{t+\delta_\epsilon} \mu_{q,\omega}^\epsilon(s) ds \sim \mu_q(t)?$$

If $\mu_{q,\omega}^\epsilon(s) = \mu_{q,\omega}(s)$,

$$\frac{1}{2\delta_\epsilon} \int_{t-\delta_\epsilon}^{t+\delta_\epsilon} \mu_{q,\omega}(s) ds \rightarrow \mu_{q,\omega}(t)$$

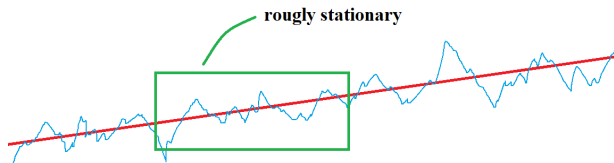
and ω is not averaged-out. But what happens when $\mu_{q,\omega}^\epsilon(s)$ oscillates faster and faster as $\epsilon \rightarrow 0$?

Example

Consider a "weakly stationary" process of the form

$$X_t^\epsilon(\omega) = X_t^{\text{st}}(\omega) + q(\epsilon t)$$

where $X_t^{\text{st}}(\omega)$ is a stationary and ergodic process with invariant measure μ and q is a continuous function. Think of the weather, perturbed by the slow increase of CO2 concentration.



Do we have convergence of time averages of the form

$$\frac{1}{T} \int_{T_0}^{T_0+T} \phi(X_t^\epsilon(\omega)) dt?$$

Solution and macroscopic reformulation

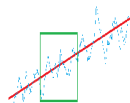
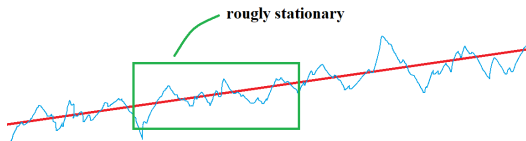
If $T_0^\epsilon = t_0/\epsilon$, $T^\epsilon = \Delta_\epsilon/\epsilon$, with $\lim_{\epsilon \rightarrow 0} \Delta_\epsilon = 0$, $\lim_{\epsilon \rightarrow 0} \Delta_\epsilon/\epsilon = \infty$, we get

$$\lim_{\epsilon \rightarrow 0} \frac{1}{T^\epsilon} \int_{T_0^\epsilon}^{T_0^\epsilon + T^\epsilon} \phi(X_t^\epsilon(\omega)) dt = \int \phi(x + q(t_0)) \mu(dx).$$

Macroscopic view:

$$Y_t^\epsilon(\omega) = X_{t/\epsilon}^\epsilon(\omega) = X_{t/\epsilon}^{\text{st}}(\omega) + q(t).$$

$$\lim_{\epsilon \rightarrow 0} \frac{1}{\Delta_\epsilon} \int_{t_0}^{t_0 + \Delta_\epsilon} \phi(Y_t^\epsilon(\omega)) dt = \int \phi(x + q(t_0)) \mu(dx).$$



Summary and plan of the lecture

- In the first lecture we have seen the definition of non-autonomous dynamical system (NADS), the corresponding definition of pull-back-attractor, and of time-dependent random measure
- and we discussed heuristically weather and climate formulating a link. The pull-back-attractor will be our main instrument to prove such a link.
- Today we concentrate on NADS and their pull-back-attractor.
- We recall the definitions, give conditions for existence
- and show three examples.

By *Non Autonomous Dynamical System (NADS)* with two external inputs we mean the following structure:

- ① a set \mathcal{Q} , a probability space $(\Omega, \mathcal{F}, \mathbb{P})$ and a metric space (X, d)
- ② a family of continuous maps $U_{q,\omega}(t_0, t) : X \rightarrow X$, indexed by $t_0 \leq t \in \mathbb{R}$ and $(q, \omega) \in \mathcal{Q} \times \Omega$, such that for all (q, ω) we have

$$U_{q,\omega}(t_0, t_0) = \text{Id} \quad \text{for all } t_0 \in \mathbb{R}$$

$$U_{q,\omega}(t_0, t) = U_{q,\omega}(s, t) \circ U_{q,\omega}(t_0, s) \quad \text{for all } t_0 \leq s \leq t \in \mathbb{R}$$

and such that for every $q \in \mathcal{Q}$ and $x \in X$ the map

$$(\omega, t_0, t) \mapsto U_{q,\omega}(t_0, t)(x)$$

is measurable.

Summarizing the notations, a NADS is:

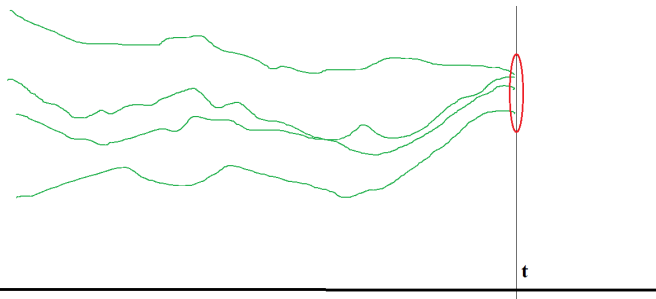
$$(\mathcal{Q}, (\Omega, \mathcal{F}, \mathbb{P}), (X, d), U_{q,\omega}(t_0, t)).$$

Attractors of NADS

Definition

We call pull-back omega-limit set of B at time t the set

$$\begin{aligned}\Omega_{q,\omega}(B, t) &= \overline{\bigcap_{s_0 \leq 0} \bigcup_{s \leq s_0} U_{q,\omega}(s, t)(B)} \\ &= \{y \in X : \exists x_n \in B, s_n \rightarrow -\infty, U_{q,\omega}(s_n, t)(x_n) \rightarrow y\}.\end{aligned}$$



Attractors of NADS (PBCGA)

Definition

Given the NADS $U_{q,\omega}(s, t) : X \rightarrow X$, we say that a family of sets

$$A_{q,\omega}(t) \quad t \in \mathbb{R}$$

is a pull-back global compact attractor (PBCGA) if:

- i) $A_{q,\omega}(t)$ is compact for every $t \in \mathbb{R}$;
- ii) $A_{q,\omega}(\cdot)$ is invariant: $U_{q,\omega}(s, t)(A_{q,\omega}(s)) = A_{q,\omega}(t)$ for every $s \leq t, s, t \in \mathbb{R}$;
- iii) $A_{q,\omega}(\cdot)$ pull-back attracts bounded sets:

$$\Omega_{q,\omega}(B, t) \subset A_{q,\omega}(t)$$

for all bounded set $B \subset X$.

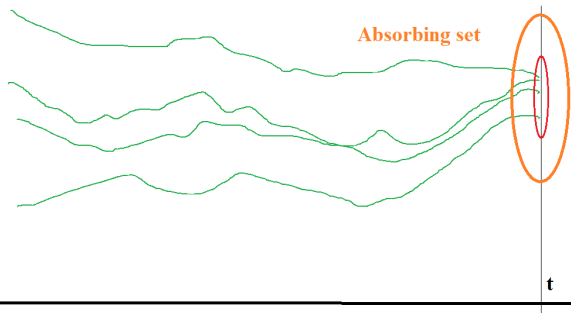
Absorbing set

Definition

A family of sets $D_{q,\omega}(t)$, $t \in \mathbb{R}$ is called a bounded (resp. compact) pull-back absorbing family if:

- i) $D_{q,\omega}(t)$ is bounded (resp. compact) for every $t \in \mathbb{R}$;
- ii) for every $t \in \mathbb{R}$ and every bounded set $B \subset X$ there exists $t_B < t$ such that

$$U_{q,\omega}(s, t)(B) \subset D_{q,\omega}(t) \quad \text{for every } s < t_B.$$



Main results on attractors

Theorem

Let $U_{q,\omega}(s, t)$ be a continuous NADS. Assume that there exists a compact pull-back absorbing family. Then a PBCGA exists, with $A_{q,\omega}(t) \subset D_{q,\omega}(t)$.

In infinite dimensions the following lemma is very useful. There are generalizations to the so-called asymptotic compactness.

Lemma

Let $U_{q,\omega}(s, t)$ be a continuous NADS. Assume that:

- i) (compact NADS) for every t and bounded set $B \subset X$, the set $\overline{U_{q,\omega}(t, t+1)(B)}$ is compact;*
- ii) there exists a pull-back absorbing family.*

Then there exists a compact pull-back absorbing family.

Example 1 (elementary)

In \mathbb{R}^d , with norm $\|\cdot\|$ and inner product $\langle \cdot, \cdot \rangle$, consider the deterministic equation (already introduced in the first lecture)

$$\frac{dx_t}{dt} = Ax_t + F(x_t) + q(t)$$

where A is a negative definite matrix, q is a continuous function in \mathbb{R}^d , F is locally Lipschitz with

$$\begin{aligned} -\langle Ax, x \rangle &\geq \nu \|x\|^2 & \nu > 0 \\ \langle F(x), x \rangle &\leq C \end{aligned}$$

for some constant $C \geq 0$. It generates a NADS $U_q(t_0, t)$. We have

$$\begin{aligned} \frac{1}{2} \frac{d}{dt} \|x_t\|^2 &= \langle Ax_t, x_t \rangle + \langle F(x_t) + q(t), x_t \rangle \\ \frac{1}{2} \frac{d}{dt} \|x_t\|^2 &\leq (-\nu + \epsilon) \|x_t\|^2 + C + \frac{1}{\epsilon} \|q(t)\|^2 \end{aligned}$$

Example 1 (elementary)

From

$$\frac{d}{dt} \|x_t\|^2 \leq 2(-\nu + \epsilon) \|x_t\|^2 + 2C + \frac{2}{\epsilon} \|q(t)\|^2$$

by choosing $\epsilon = \nu/2$ we get

$$\frac{d}{dt} \|x_t\|^2 \leq -\nu \|x_t\|^2 + 2C + \frac{4}{\nu} \|q(t)\|^2$$

and we deduce

$$\|U_q(t_0, t)(x_0)\|^2 \leq e^{(t-t_0)\nu} \|x_0\|^2 + \int_{t_0}^t e^{(t-s)\nu} \left(2C + \frac{4}{\nu} \|q(s)\|^2 \right) ds.$$

Assume q has sub-exponential growth at $-\infty$. The set

$D_q(t) = B(0, R_q(t))$ is an absorbing set, with

$$R_q(t)^2 = 1 + \int_{-\infty}^t e^{(t-s)\nu} \left(2C + \frac{4}{\nu} \|q(s)\|^2 \right) ds.$$

Example 2 (easy)

In \mathbb{R}^d , with norm $\|\cdot\|$ and inner product $\langle \cdot, \cdot \rangle$, consider the stochastic equation

$$dX_t = (AX_t + F(X_t, t)) dt + \sqrt{Q} dW_t$$

where A is a negative definite matrix, F is continuous and Lipschitz in X_t uniformly in t , W is a two-sided Brownian motion in \mathbb{R}^d , Q is a nonnegative symmetric matrix, and

$$\langle F(v + z, t), v \rangle \leq C_2(t) (\|z\|^p + 1) - \frac{1}{2} \langle Av, v \rangle$$

for some powers $p \geq 1$, a function $C_2(t) > 0$ with sub-exponential growth at $-\infty$.

Example 2 (easy)

Recall from the first lecture that in order to define the NADS, we introduced a solution of the equation

$$dZ_t = AZ_t dt + \sqrt{Q} dW_t.$$

Let us take the stationary solution, written ω -wise:

$$Z_t(\omega) := \int_{-\infty}^t A e^{A(t-s)} \sqrt{Q} W_s(\omega) ds + \sqrt{Q} W_t(\omega).$$

It is well defined if we restrict the space Ω to those points ω such that $s \mapsto W_s(\omega)$ has sub-exponential growth as $s \rightarrow -\infty$.

Example 2 (easy)

Then, called $V_t^{t_0, x_0}(\omega)$ the ω -wise solution to the Cauchy problem

$$\begin{aligned}\frac{dV_t}{dt} &= AV_t + F(V_t + Z_t(\omega), t) \\ V_{t_0} &= x_0 - Z_{t_0}(\omega)\end{aligned}$$

we define the NADS as

$$U_\omega(t_0, t)(x_0) = V_t^{t_0, x_0}(\omega) + Z_t(\omega).$$

Example 2 (easy)

In order to prove the existence of an absorbing set and thus an attractor, we compute

$$\begin{aligned} & \frac{1}{2} \frac{d}{dt} \|V_t^{t_0, x_0}(\omega)\|^2 - \langle AV_t^{t_0, x_0}(\omega), V_t^{t_0, x_0}(\omega) \rangle \\ &= \langle F(V_t^{t_0, x_0}(\omega) + Z_t(\omega), t), V_t^{t_0, x_0}(\omega) \rangle \\ &\leq C_2(t) (\|Z_t(\omega)\|^p + 1) - \frac{1}{2} \langle AV_t^{t_0, x_0}(\omega), V_t^{t_0, x_0}(\omega) \rangle. \end{aligned}$$

Calling $\nu > 0$ the best constant such that

$$-\langle Av, v \rangle \geq \nu \|v\|^2$$

we have proved

$$\frac{1}{2} \frac{d}{dt} \|V_t^{t_0, x_0}(\omega)\|^2 \leq \frac{\nu}{2} \|V_t^{t_0, x_0}(\omega)\|^2 + C_2(t) (\|Z_t(\omega)\|^p + 1)$$

Example 2 (easy)

Hence

$$\begin{aligned} \|V_t^{t_0, x_0}(\omega)\|^2 &\leq e^{(t-t_0)\nu/2} \|x_0 - Z_{t_0}(\omega)\|^2 \\ &\quad + \int_{t_0}^t e^{(t-s)\nu/2} C_2(s) (\|Z_s(\omega)\|^p + 1) ds. \end{aligned}$$

It follows

$$\begin{aligned} \|U_\omega(t_0, t)(x_0)\|^2 &\leq 2e^{(t-t_0)\nu/2} \|x_0 - Z_{t_0}(\omega)\|^2 \\ &\quad + 2 \int_{t_0}^t e^{(t-s)\nu/2} C_2(s) (\|Z_s(\omega)\|^p + 1) ds \\ &\quad + 2 \|Z_t(\omega)\|^2. \end{aligned}$$

Example 2 (easy)

Notice that, from the analogous property of $W_t(\omega)$, the function $t_0 \mapsto \|Z_{t_0}(\omega)\|^2$ has subexponential growth as $t_0 \rightarrow -\infty$. Taking the limit as $t_0 \rightarrow -\infty$ we get that a random bounded (hence with compact closure, being in \mathbb{R}^d) absorbing set $D_\omega(t)$ exists, contained in the ball $B(0, R_t(\omega))$ with

$$\begin{aligned} R_t(\omega)^2 &= 2 \int_{-\infty}^t e^{(t-s)\nu/2} C_2(s) (\|Z_s(\omega)\|^p + 1) ds \\ &\quad + 2 \|Z_t(\omega)\|^2 + 1. \end{aligned}$$

Then the attractor $A_\omega(t) \subset B(0, R_t(\omega))$ exists.

Example 3 (difficult)

In \mathbb{R}^d , with norm $\|\cdot\|$ and inner product $\langle \cdot, \cdot \rangle$, consider the stochastic equation

$$dX_t = (AX_t + B(X_t, X_t)) dt + \sqrt{Q} dW_t$$

where A is a negative definite matrix, $B : \mathbb{R}^d \times \mathbb{R}^d \rightarrow \mathbb{R}^d$ is bilinear, W is a two-sided Brownian motion in \mathbb{R}^d , Q is a nonnegative symmetric matrix, and

$$\langle B(x, v), v \rangle = 0.$$

This finite dimensional system simulates the difficulties of the Navier-Stokes equations.

Compared to our previous example, setting $F(x, t) = B(x, x)$, do we have

$$\langle F(v + z, t), v \rangle \leq C_2(t) (\|z\|^p + 1) - \frac{1}{2} \langle Av, v \rangle?$$

Example 3 (difficult)

We now have

$$\begin{aligned}\langle F(v+z, t), v \rangle &= \langle B(v+z, v), v \rangle + \langle B(v+z, z), v \rangle \\ &= \langle B(v+z, z), v \rangle \\ &= \langle B(v, z), v \rangle + \langle B(z, z), v \rangle \\ &\leq C \|z\| \|v\|^2 + C \|z\|^2 \|v\| \\ &\leq (C \|z\| + \epsilon) \|v\|^2 + \frac{C^2}{\epsilon} \|z\|^4\end{aligned}$$

but we need

$$\langle F(v+z, t), v \rangle \leq C_2(t) (\|z\|^p + 1) - \frac{1}{2} \langle Av, v \rangle.$$

It is impossible to estimate $C \|z\| \|v\|^2$ by $-\frac{1}{2} \langle Av, v \rangle$ independently of z .

Example 3 (difficult)

Repeat step by step all the computations of the first example, getting

$$\begin{aligned} & \frac{1}{2} \frac{d}{dt} \|V_t^{t_0, x_0}(\omega)\|^2 + \nu \|V_t^{t_0, x_0}(\omega)\|^2 \\ & \leq (C \|Z_t(\omega)\| + \epsilon) \|V_t^{t_0, x_0}(\omega)\|^2 + \frac{C^2}{\epsilon} \|Z_t(\omega)\|^4. \end{aligned}$$

This gives us

$$\begin{aligned} \|V_t^{t_0, x_0}(\omega)\|^2 & \leq e^{\int_{t_0}^t (-\nu + C \|Z_r(\omega)\| + \epsilon) dr} \|x_0 - Z_{t_0}(\omega)\|^2 \\ & \quad + \int_{t_0}^t e^{\int_s^t (-\nu + C \|Z_r(\omega)\| + \epsilon) dr} \frac{C^2}{\epsilon} \|Z_s(\omega)\|^4 ds. \end{aligned}$$

Clearly the Gaussian process $Z_r(\omega)$ is sometimes so large that $C \|Z_r(\omega)\|$ is larger than ν and thus the exponent becomes positive (expanding). However, if this happens not so often, in the time-average we have a contraction.

But why should $C \|Z_r(\omega)\|$ be smaller than ν most of the time?

The solution in the next lecture.

Definition

We say that $A(t)$ attracts B at time t if for every $\epsilon > 0$ there exists $s_0 < 0$ such that for all $s < s_0$ we have

$$U(s, t)(B) \subset \mathcal{U}_\epsilon(A(t)).$$

We say that a family of sets $\{A(t), t \in \mathbb{R}\}$ attracts B if the set $A(t)$ attracts B at time t , for every $t \in \mathbb{R}$.

This definition can be formulated by means of the non-symmetric distance between sets. Given $A, B \subset X$ define

$$d(B, A) = \sup_{x \in B} d(x, A), \quad d(x, A) = \inf_{y \in A} d(x, y).$$

Then $A(t)$ attracts B if

$$\lim_{s \rightarrow -\infty} d(U(s, t)(B), A(t)) = 0.$$

Theorem

Assume $A(t)$ is compact. Then $A(t)$ attracts B if and only if $\Omega(B, t) \subset A(t)$.

(Proof by exercise)

Theorem

In general,

$$U(s, t) \Omega(B, s) \subseteq \Omega(B, t).$$

If there is a compact absorbing family, then

$$U(s, t) \Omega(B, s) = \Omega(B, t).$$

Example of proof

The proof that $U(s, t) \Omega(B, s) \subseteq \Omega(B, t)$ is left as an exercise. Let us show that, under the assumption of existence of a compact absorbing set, we also have

$$\Omega(B, t) \subseteq U(s, t) \Omega(B, s).$$

Take $z \in \Omega(B, t)$ and $x_n \in B$, $s_n \rightarrow -\infty$ such that

$$U(s_n, t)(x_n) \rightarrow z.$$

Then

$$U(s, t) U(s_n, s)(x_n) \rightarrow z.$$

The existence of a compact absorbing set implies that $U(s_n, s)(x_n)$ is included, eventually, in a compact set, hence there is a convergent subsequence $U(s_{n_k}, s)(x_{n_k}) \rightarrow y$, hence $y \in \Omega(B, s)$ and $z = U(s, t)y$, therefore $\Omega(B, t) \subseteq U(s, t) \Omega(B, s)$.

Proof of the main theorem

We have to prove that existence of a compact pull-back absorbing family implies existence of a PBCGA. Set

$$A(t) = \overline{\bigcup_{B \text{ bounded}} \Omega(B, t)}.$$

Let us prove it fulfills all properties of a PBGCA. By definition, $\Omega(B, t) \subset A(t)$ for every B , hence we have pull-back attraction. From property (ii) of absorbing set,

$$\Omega(B, t) \subset D(t)$$

for every t and every bounded set B . In particular,

$$\overline{\bigcup_{B \text{ bounded}} \Omega(B, t)} \subset \overline{D(t)} = D(t).$$

Hence $A(t) \subset D(t)$ namely it is compact (being closed subset of a compact set).

Proof of the main theorem (cont.)

Forward invariance, $U(s, t) A((s)) \subset A(t)$ is a consequence of forward invariance of omega-limit sets, $U(s, t) \Omega(B, s) \subset \Omega(B, t)$, plus a general property on the image of a union of sets, plus the continuity of $U(s, t)$ to deal with the closure, being $A(t) = \overline{\bigcup \Omega(B, t)}$.

The opposite inclusion

$$A(t) \subset U(s, t) A((s))$$

is the most tricky step of the proof. Let $z \in A(t)$. There exists a sequence of bounded sets B_n and points $z_n \in \Omega(B_n, t)$ such that

$$z = \lim_{n \rightarrow \infty} z_n.$$

Each z_n is equal to

$$z_n = \lim_{k \rightarrow \infty} U(s_k^n, t) (x_k^n)$$

where $\lim_{k \rightarrow \infty} s_k^n = -\infty$ and $(x_k^n)_{k \in \mathbb{N}} \subset B_n$. Hence

$$z_n = \lim_{k \rightarrow \infty} U(s, t) (y_k^n), \quad y_k^n := U(s_k^n, s) (x_k^n).$$

Proof of the main theorem (cont.)

The existence of a compact absorbing set $D(s)$ implies that there exists a subsequence $(y_{k_m^n}^n)_{m \in \mathbb{N}}$ with a limit

$$y^n = \lim_{m \rightarrow \infty} y_{k_m^n}^n$$
$$y^n \in D(s).$$

Then, by continuity of $U(s, t)$,

$$z_n = U(s, t) y^n.$$

Again by compactness of $D(s)$ there is a subsequence $(y^{n_j})_{j \in \mathbb{N}}$ with a limit $y \in D(s)$. By continuity of $U(s, t)$,

$$z = U(s, t) y.$$

It remains to check that $y \in A(s)$, not difficult as an exercise.

About uniqueness

The attraction property has a strong power of identification, with respect to the poor property of invariance. However, given a global attractor $A(t)$ we may always add to it trajectories $\{x(t)\}$ and still have all properties, because compactness and invariance are satisfied and attraction continues to hold when we enlarge the attracting sets. One way to escape this artificial non-uniqueness is by asking for a property of *minimality*.

Definition

We say that a global compact attractor $A(t)$ is minimal if any other global compact attractor $A'(t)$ satisfies

$$A(t) \subset A'(t)$$

for all $t \in \mathbb{R}$.

When it exists, the minimal global compact attractor is obviously unique.

Existence (and uniqueness) of a minimal attractor

Theorem

Under the assumptions of the main existence Theorem, the attractor

$$A(t) = \overline{\bigcup_{B \text{ bounded}} \Omega(B, t)}$$

is minimal.

The proof is elementary. In the notes there is also another uniqueness criterion based on a different property.

Summary and perspective

- We have developed a theory of attractors for NADS
- and have seen a few examples (full solution of the Navier-Stokes one next time).
- Next time we complete that example
- and understand the concept of random measure, supported on the random attractor.
- Moreover, we go back to the main formula relating weather and climate.

Thank you for your attention

